Торіс		Ref	Ex
Matrices and Transformations	 Introduction to Matrices Add, subtract and multiply conformable matrices. Multiply a matrix by a scalar. Understand and use zero and identity matrices. 	P3.1 P3.2	
	 Matrices and Transformations Find the 2x2 matrix associated with a linear transformation and vice versa. Reflection in coordinate axes and lines y = ± x Rotation through any angle about (0, 0) Stretches parallel to the x-axis and y-axis Enlargement about centre (0, 0), with scale factor k, (k ≠ 0). Successive transformations – A followed by B is represented by the matrix BA. Find 3x3 matrices representing 3D transformations Reflection in plane x=0, y=0 or z=0 Rotations through multiples of 90° about the x, y or z axes. 	P3.3	
	 Invariant Points Find co-ordinates of invariant points for a given transformation Find equations of invariant lines for a given transformation 	P3.4	
	Matrices and Transformations Assessment	I	
Complex Numbers	 Introduction to Complex Numbers Understand the definition of a complex number Understand and use the terms real part and imaginary part. Add, subtract, multiply and divide complex numbers in the form <i>x+iy</i> with <i>x</i> and <i>y</i> real Find the complex conjugate Solve any quadratic equation with real coefficients. Know that the non-real roots of quadratic equations (with real coefficients) form a conjugate pair Find the square root of a complex number 	P2.1 P2.2 P2.3	
	 Use and interpret Argand diagrams. Represent the sum or difference of two complex numbers on an Argand diagram. Complex Numbers Assessment 		

Торіс		Ref	Ex		
Matrices and their Inverses	 2x2 Matrices Calculate the determinant of a 2x2 matrix Use the property det AB = det A x det B Know that the magnitude of the determinant of a 2x2 matrix gives the area scale factor of the associated transformation, and that the sign of the determinant indicates whether the orientation of the image is preserved or reversed. Understand what is meant by a singular matrix and a non-singular matrix Calculate the inverse of a 2x2 matrix Prove and use the property (AB) ⁻¹ = B ⁻¹ A ⁻¹ 	P3.5 P3.6			
	 3x3 Matrices Calculate the determinant of a 3x3 matrix either manually or using the matrix facility on a calculator. Know that the magnitude of the determinant of a 3x3 matrix gives the volume scale factor of the associated transformation, and that the sign of the determinant indicates whether the orientation of the image is preserved or reversed. Calculate the inverse of a 3x3 matrix either manually or using the matrix facility on a calculator. 	P3.5 P3.6 P3.7			
	 Matrices and Simultaneous Equations Solve three linear simultaneous equations in three variables by use of the inverse matrix Interpret geometrically the solution and failure of solution of three simultaneous linear equations. meet in a point form a sheaf form a prism or are otherwise inconsistent 	P3.7 P3.8			
	Matrices and their Inverses Assessment				
Roots of polynomials	 Roots and coefficients Know about the relationships between roots and coefficients of quadratic, cubic and quartic equations. Be able to form a new equation whose roots are related to the roots of a given equation by a linear transformation. 	P4.1 P4.2			
	 Complex Roots of Polynomials Understand that non-real roots of polynomial equations with real coefficients occur in conjugate pairs. Be able to solve cubic or quartic equations with real coefficients. 	P2.1			
Roots of Polynomials Assessment					

Торіс		Ref	Ex
Complex Numbers and Geometry	 Modulus and Argument Find the modulus and argument of a complex number Convert between the Cartesian form and the modulus- argument form of a complex number. Multiply and divide complex numbers in modulus- argument form 	P2.5 P2.6	
	 Loci in the complex plane To construct and interpret simple loci in the Argand diagram. z-a =r Arg (z-a) = β z-a = z-b Understand and use Radians as an alternative angle measure. 	P2.7	
	Complex Numbers and Geometry Assessment		
Sequences, Series and Proof	 Summing Series Understand and use formulae for the sums of integers, squares and cubes and use these to sum other series. 	P4.3	
	 Proof by Induction Construct proofs using mathematical induction. Contexts include sums of series, divisibility and powers of matrices. 	P1.1	
	Sequences and Series Assessment		
Vectors and 3-D Space	 The Scalar Product Calculate the scalar product of two vectors Use the scalar product to find the angle between two vectors Check whether two vectors are perpendicular using the scalar product. 	P6.3 P6.4	
	 The Equation of a Line Express the equation of a line in three dimensions in vector form and in Cartesian form Calculate the angle between two lines using the scalar product Find the point of intersection of two straight lines given in vector form Understand that two lines in three dimensions may either intersect, be parallel or be skew 	P6.1	
	 The Equation of a Plane Form and use vector and Cartesian equations of a plane Convert between the different forms for the equation of a plane Understand that a vector which is perpendicular to a plane is perpendicular to any vector in the plane Find the angle between two planes by finding the angle between their normals Find the angle between a line and a plane Find the point of intersection of a line and a plane 	P6.2 P6.3 P6.5	

Торіс		Ref	Ex
Vectors and 3-D Space (cont.)	 Finding Distances Find the perpendicular distance from a point to a plane Find the perpendicular distance from a point to a line Find the perpendicular distance between two lines 	P6.5	
Vectors and 3-D Space Assessment			
Further Calculus	 Volumes of Revolution Calculate the volume of a solid of revolution formed by rotating a plane region about the x-axis or y-axis. Derive the formulae for calculating the volume of revolution. 	P5.1	
Further Calculus Assessment			